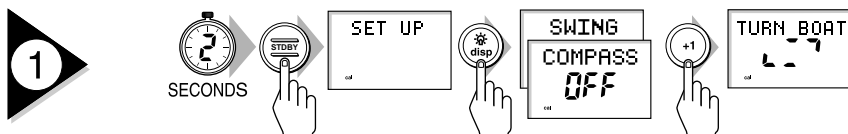


Distributed by  
**Raymarine**

Any reference to Raytheon or RTN in this manual should be interpreted as Raymarine. The names Raytheon and RTN are owned by the Raytheon Company.

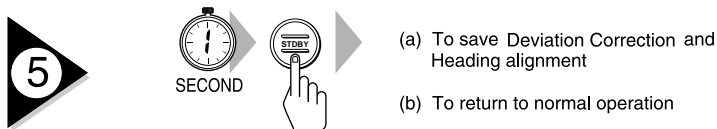
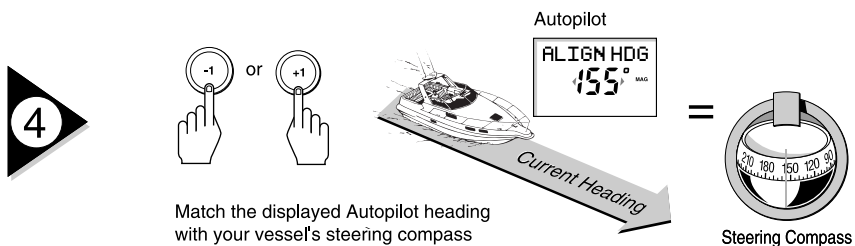
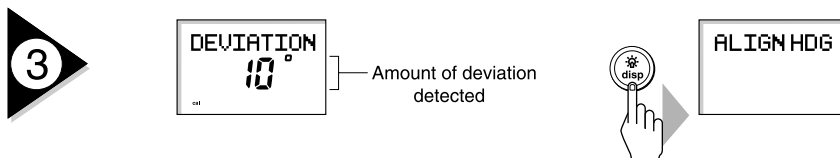
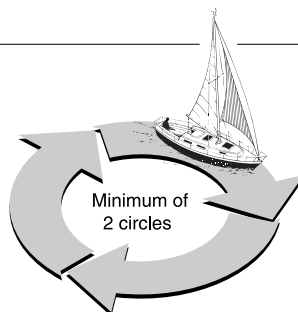
# ST4000, 5000 & 6000 Plus

## Compass Deviation Correction & Heading Alignment



- 2**
- (a) Turn your boat in circles
  - (b) Keep your boat speed below 2 knots
  - (c) Keep turning your boat until the deviation screen is displayed (see 3 below)

Note: One complete circle should take at least 3 minutes

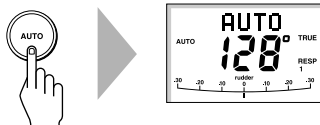


# ST4000, 5000 & 6000 Plus

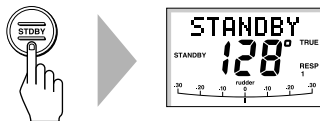
## Quick Reference Guide to Basic Operation

This is only a quick reference guide to basic operation and calibration (overleaf). For full details, please refer to the appropriate chapters in the Operation and Installation handbook.

### Engaging the Autopilot (Auto mode)

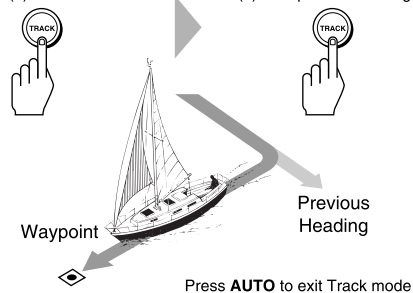


### Disengaging the Autopilot (Standby mode)

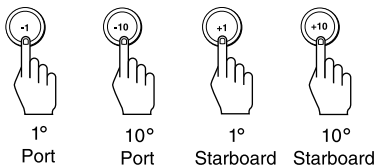


### Engaging Track Mode from Auto

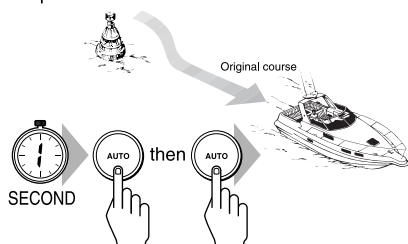
- (1) Enter Track Mode (2) Accept New Heading



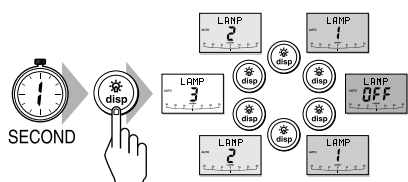
### Making course changes in Auto mode



### Returning to the previous Autopilot heading after a dodge manoeuvre executed with the pilot in Auto mode



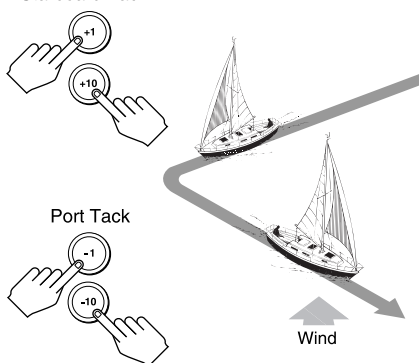
### Illumination - Switching ON/OFF and Making Adjustments



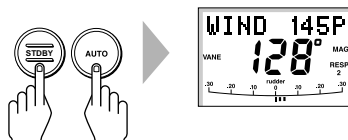
The display times-out to normal operation after 7 seconds of keypad inactivity.

### Engaging the Automatic Tack Feature

#### Starboard Tack



### Selecting Vane mode (WindTrim) from Standby and Auto modes



### Returning to the previous apparent wind angle (e.g. after a dodge manoeuvre)

