kinematics equations

UNIT 2 and 3 CP EQUATIONS

Var	Given value	Units	Description
Δx		m	displacement
Xf		m	final position
Xi		m	initial position
speed _{ave}		m s	average speed
d		m	distance
t		S	time
$\nu_{\rm ave}$		m/s	average velocity
Δν		<u>m</u> s	change in velocity
V_{f}		m/s	final velocity
Vi		<u>m</u> s	initial velocity
а		<u>m</u> s	acceleration

$$\Delta x = x_{\rm f} - x_{\rm i}$$

$$speed_{ave} = \frac{d}{t}$$

$$V_{\text{ave}} = \frac{\Delta x}{t}$$

$$\Delta \nu = \nu_{\rm f} - \nu_{\rm i}$$

kinematics equations (continued)

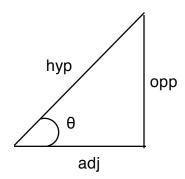
$$a = \frac{\Delta v}{t}$$

$$v_{\rm f} = v_{\rm i} + at$$

$$\Delta x = \frac{1}{2} a t^2$$

dynamics equations

UNIT 4 and 5 CP EQUATIONS



Remember! SOH CAH TOA

Var	Given value	Units	Description
θ		0	angle in degrees
opp			side opposite of angle
hyp			longest side of a right triangle
adj			side adjacent to angle

$$\sin \theta = \frac{opp}{hyp}$$

$$\cos\theta = \frac{adj}{hyp}$$

$$\tan\theta = \frac{opp}{adj}$$

dynamics equations (continued)

Var	Given value	Units	Description
weight		N	force of gravity on object
m		kg	mass
\mathcal{G}	10	m s ²	acceleration due to gravity
F _{NET}		N	net or total force
а		m s	acceleration
f		N	force of friction
μ			coefficient of friction
N		N	normal force

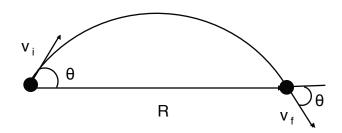
$$weight = mg$$

$$F_{NET} = ma$$

$$f = \mu N$$

projectile and circular motion equations

UNIT 6 and 8 CP EQUATIONS



Var	Given value	Units	Description
R		m	range of a projectile
V _i		<u>m</u> s	launch velocity of a projectile
Vf		<u>m</u> s	impact velocity of a projectile
g	10	<u>m</u> s ²	acceleration due to gravity
θ		0	launch angle with respect to the horizontal

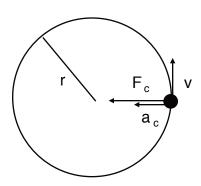
$$V_i = V_f$$

$$time_{up} = time_{down}$$

$$R = \left(\frac{v_i^2}{g}\right) \sin(2\theta)$$

projectile and circular motion equations (continued)

Var	Given value	Units	Description
V		<u>m</u> s	tangential velocity or linear speed
r		m	radius of circular path
T		Ø	period – time to go around circle once
a _c		m s ²	centripetal acceleration
F _c		N	centripetal force – net force towards the center of the circle
m		kg	mass



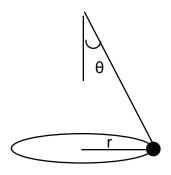
$$V = \frac{2\pi r}{T}$$

$$a_{c} = \frac{v^{2}}{R}$$

$$F_c = ma_c$$

projectile and circular motion equations (continued)

This formula is for a conical pendulum aka the Flying Pig!



 Var	Given value	Units	Description
θ		0	angle string makes with the vertical

$$\tan\theta = \frac{v^2}{rg}$$

work and energy equations

UNIT 7 CP EQUATIONS

Var	Given value	Units	Description
work		J	work
F		N	force in the direction of Δx
Δx		m	displacement
ΔE		J	change in energy of a system
E_{g}		J	gravitational potential energy
m		kg	mass
\mathcal{G}	10	m s ²	acceleration due to gravity
h		m	height above reference point
E_{k}		J	kinetic energy
E_{el}		J	elastic potential energy
K		<u>N</u>	spring constant
Δx_{s}		m	amount spring is stretched
F_{s}		N	force required to stretch a spring
power		W	power, the rate at which work is done
t		t	time
V		m s	velocity

 $work = \Delta E$

 $work = area under F vs \Delta x curve$

work and energy equations (continued)

$$work = F\Delta x$$

$$E_g = mgh$$

$$E_{\rm k} = \frac{1}{2} m v^2$$

$$E_{\rm el} = \frac{1}{2} k \Delta x_{\rm s}^2$$

$$F_s = k\Delta x_s$$

$$power = \frac{work}{t}$$

$$power = Fv$$

momentum equations

Var	Given value	Units	Description
p		kg m s	momentum
m		kg	mass
V		m s	velocity
impulse		Ns	impuse
F		N	applied force
t		S	time
Δρ		kgm s	change in momentum
V_{f}		<u>m</u> s	final velocity
ν_{i}		<u>m</u> s	initial velocity

$$p = m v$$

$$impulse = Ft$$

$$impulse = \Delta p$$

$$\Delta \rho = m(\nu_{\rm f} - \nu_{\rm i})$$

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momentum equations (continued)

conservation of momentum for a system of two objects (sum of initial momenta = sum of final momenta)

$$m_1 V_{1i} + m_2 V_{2i} = m_1 V_{1f} + m_2 V_{2f}$$

For an elastic collision, kinetic energy is also conserved.

$$sum of E_{ki} = sum of E_{kf}$$

For a completely inelastic collision where objects stick together after collision:

$$m_1 V_{1i} + m_2 V_{2i} = (m_1 + m_2) V_f$$

conservation of momentum for an explosion (like firing a gun) where the system was initially at rest:

$$0 = m_1 v_{1f} + m_2 v_{2f}$$