

Sample Exam 1

1. a) Take $t=0$, this gives a point $Q = (1, 2, 0)$ on the line. Also we have $P = (4, 1, 1)$ in the plane (note Q is in the plane also). The direction vector of the line $\vec{v} = \langle 1, -1, 4 \rangle$ and \vec{PQ} are both in the plane, hence

$$\begin{aligned}\vec{n} &= \vec{v} \times \vec{PQ} = \langle 1, -1, 4 \rangle \times \langle -3, 1, -1 \rangle = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & -1 & 4 \\ -3 & 1 & -1 \end{vmatrix} \\ &= \begin{vmatrix} 1 & 1 & 1 \\ -3 & 1 & -1 \\ 1 & -1 & 1 \end{vmatrix} \\ &= (1-3)\hat{i} - (-1+12)\hat{j} + (1-3)\hat{k} \\ &= \langle -2, -11, -2 \rangle\end{aligned}$$

a normal vector

Take P in the plane. The equation is

$$-2(x-4) - 11(y-1) - 2(z-1) = 0$$

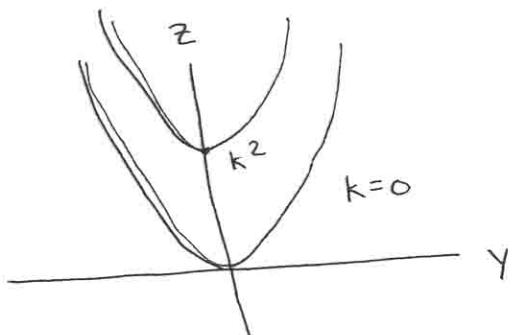
$$-2x - 11y - 2z + 21 = 0$$

$$2x + 11y + 2z - 21 = 0$$

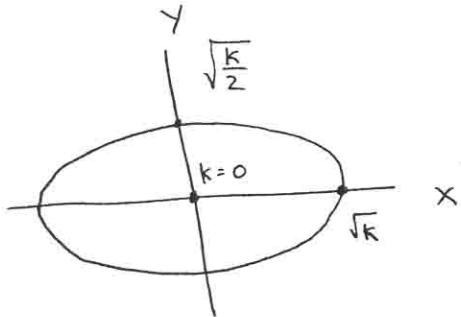
b) IGNORE!

$$x^2 + 2y^2 - z^2 = 0$$

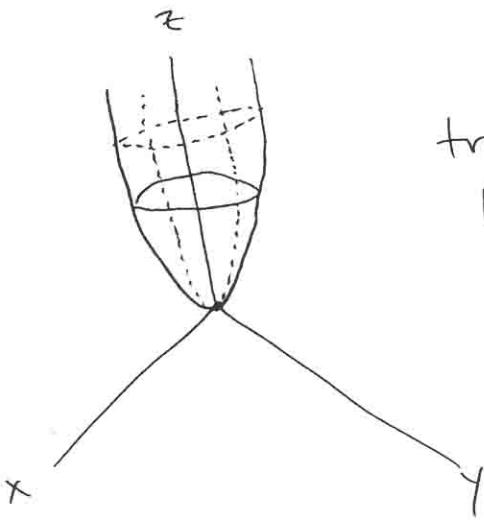
a) $x=k$: $z = \sqrt{2}y^2 + k^2$ parabolas!



b) $z=k$: $x^2 + 2y^2 = k$ ellipses $k \geq 0$



c) Elliptic paraboloid



traces are dotted lines!

$$3. \quad a) \quad \vec{r}(t) = \left\langle \frac{1}{t}, t^2 \right\rangle$$

$$\vec{v}(t) = \dot{\vec{r}}(t) = \left\langle -\frac{1}{t^2}, 2t \right\rangle$$

$$\text{Speed} = S = |\vec{v}(t)| = \sqrt{\frac{1}{t^4} + 4t^2}$$

$$\frac{dS}{dt} = \frac{1}{2} \left(\frac{1}{t^4} + 4t^2 \right)^{-1/2} \left(-4 \frac{1}{t^5} + 8t \right)$$

$$\left. \frac{dS}{dt} \right|_{t=1} = \frac{1}{2} (1+4)^{-1/2} (-4+8)$$

$$= \frac{2}{\sqrt{5}}$$

b) IGNORE!

1. a) If $z=0$, $x-y=2$
 $2x-y=1$ give $x-2=2x-1$
 $x=-1$
 $y=-3$
 $(-1, -3, 0)$ is on the line

If $y=0$, $x+z=2$
 $2x-z=1$ give $3x=3$
 $x=1$
 $z=1$

$(1, 0, 1)$ is on the line

b) $P(-1, -3, 0)$ $Q(1, 0, 1)$ and $R(-1, 0, 2)$

are on the plane, so we have a normal vector:

$$\begin{aligned}\vec{n} &= \vec{PQ} \times \vec{PR} = \langle 2, 3, 1 \rangle \times \langle 0, 3, 2 \rangle \\&= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 3 & 1 \\ 0 & 3 & 2 \end{vmatrix} \\&= \begin{vmatrix} 3 & 1 \\ 3 & 2 \end{vmatrix} \hat{i} - \begin{vmatrix} 2 & 1 \\ 0 & 2 \end{vmatrix} \hat{j} + \begin{vmatrix} 2 & 3 \\ 0 & 3 \end{vmatrix} \hat{k} \\&= (6-3)\hat{i} - (2 \cdot 2 - 0)\hat{j} + (6-0)\hat{k} \\&= \langle 3, -4, 6 \rangle\end{aligned}$$

and use point $Q(1, 0, 1)$:

$$3(x-1) - 4(y-0) + 6(z-1) = 0$$

$$3x - 4y + 6z - 9 = 0$$

S. a) We want t such that

$$e^{2t} = 1$$

$$e^{-t} = 1$$

$$t^2 + 4 = 4$$

clearly $t=0$ works

$$\vec{r}(0) = \langle 1, 1, 4 \rangle \quad \text{so } (1, 1, 4)$$

is on the curve

b) $\vec{r}'(t) = \langle 2e^{2t}, -e^{-t}, 2t \rangle$

$$\hat{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} = \frac{\langle 2e^{2t}, -e^{-t}, 2t \rangle}{\sqrt{4e^{4t} + e^{-2t} + 4t^2}}$$

$$\hat{T}(0) = \frac{\langle 2, -1, 0 \rangle}{\sqrt{4+1}} = \left\langle \frac{2}{\sqrt{5}}, -\frac{1}{\sqrt{5}}, 0 \right\rangle$$

z -axis given by \hat{k}

$$\text{So } \hat{T}(0) \cdot \hat{k} = \left\langle \frac{2}{\sqrt{5}}, -\frac{1}{\sqrt{5}}, 0 \right\rangle \cdot \langle 0, 0, 1 \rangle = 0$$

So orthogonal.

Note: You don't have to use the unit tangent vector here, do you see why?